## Discrete Time Control Systems 2nd Ed Ogata Solutions Manual

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$$f(t) = 0 t < 0$$
$$= t^2 e^{-at} t \ge 0$$

Note that

$$\mathcal{L}[t^2] = \frac{2}{s^3}$$

Referring to Equation (2-2), we obtain

$$F(s) = \mathcal{L}[f(t)] = \mathcal{L}[t^2e^{-at}] = \frac{2}{(s+a)^3}$$

B-2-4.

$$f(t) = 0 t < 0$$

: 0.3 2 "yt cos 3 wt t≥0

Noting that

$$\cos 2\omega t \cos 3\omega t = \frac{1}{2}(\cos 5\omega t + \cos \omega t)$$

we have

$$F(s) = \mathcal{L}[f(t)] = \mathcal{L}[\frac{1}{2}(\cos 5\omega t + \cos \omega t)]$$

$$= \frac{1}{2} \left( \frac{s}{s^2 + 25\omega^2} + \frac{s}{s^2 + \omega^2} \right) = \frac{(s^2 + 13\omega^2)s}{(s^2 + 25\omega^2)(s^2 + \omega^2)}$$

B-2-5. The function f(t) can be written as

$$f(t) = (t - a) 1(t - a)$$

The Laplace transform of f(t) is

$$F(s) = \sqrt{[f(t)]} = \sqrt{[(t-a)](t-a)]} = \frac{e^{-as}}{s^2}$$

B-2-6.

$$f(t) = c 1(t - a) - c 1(t - b)$$

The Laplace transform of f(t) is

$$F(s) = c \frac{e^{-as}}{s} - c \frac{e^{-bs}}{s} = \frac{c}{s} (e^{-as} - e^{-bs})$$

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